Ceaser 3.0 GPS Basics

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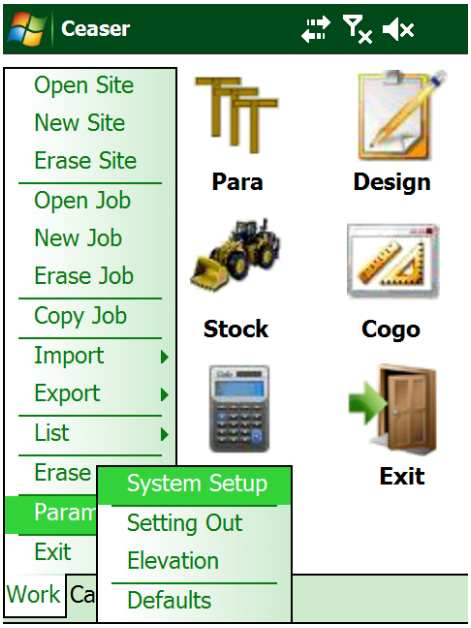
Ceaser GPS Tutorial

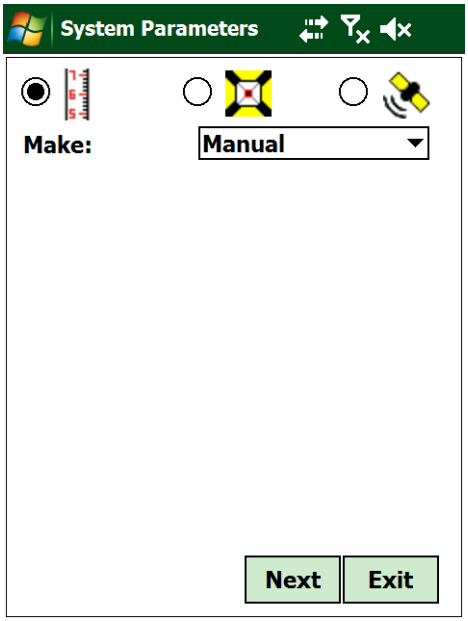
- How to connect (Bluetooth Pair) to your GPS
- How to Setup your Base and Rover
- How to Calibrate(Localize)
- How To Check your Fix Status
- How to Log a Tachy Point
- How to Setout a point

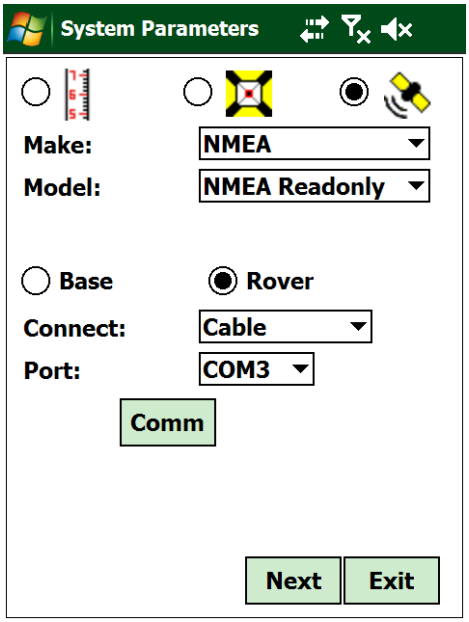
How to connect (Bluetooth Pair) to your GPS:

- From the Main Menu click ***Work > Parameters > System Setup***

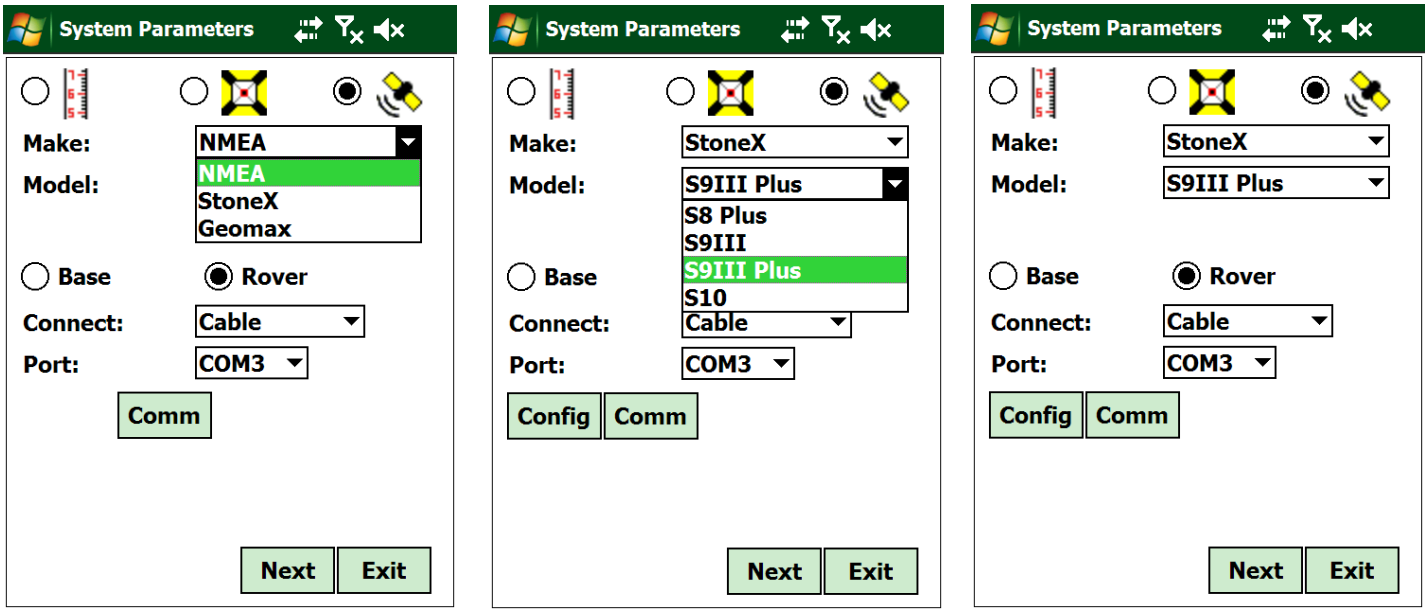


- Select GPS by clicking on the dot next to the GPS icon 

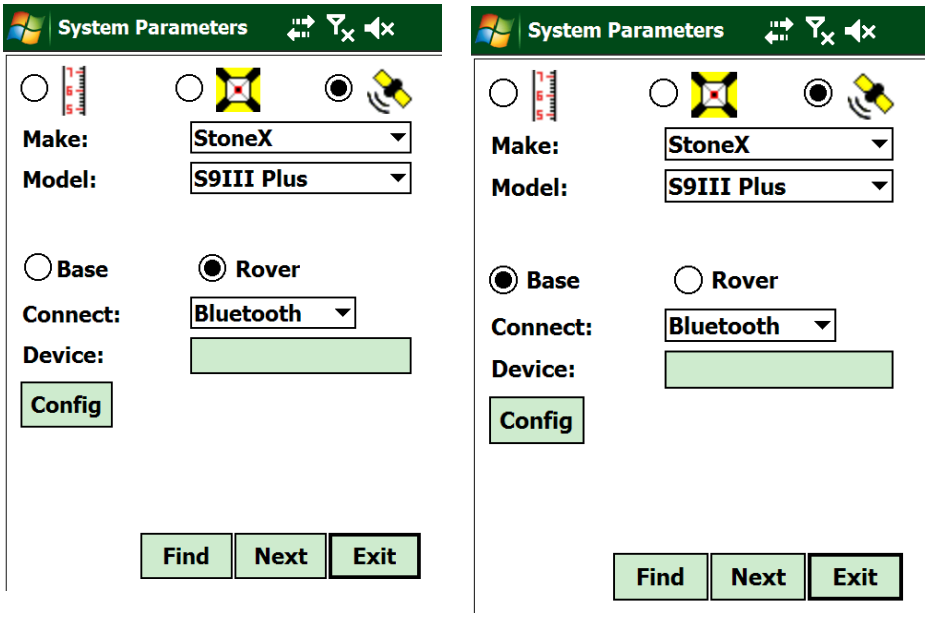




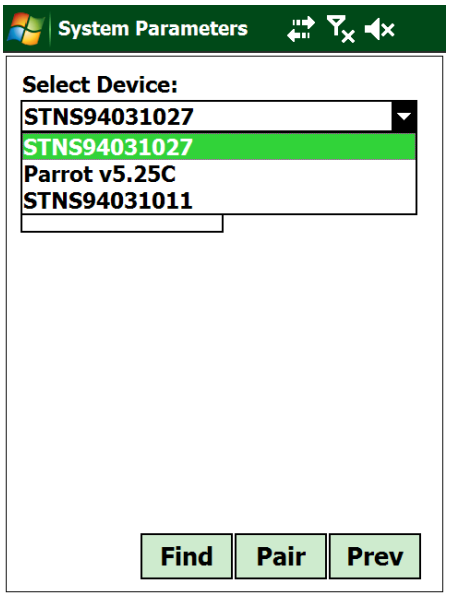
- Select the Correct Make and Model and Connection type(Cable/Bluetooth)



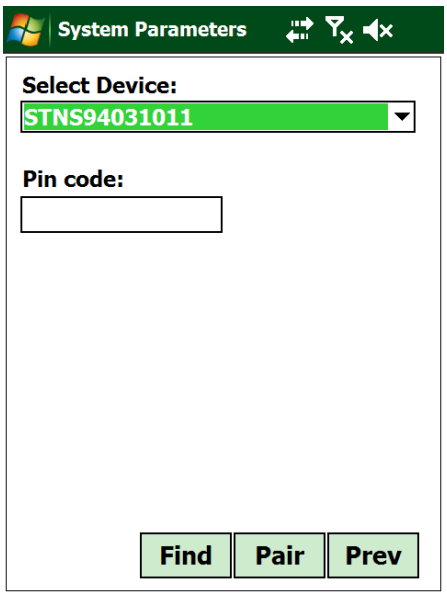
- To add your base, Click on the Circle next to the word ***Base*** ○ Base // ◉ Base

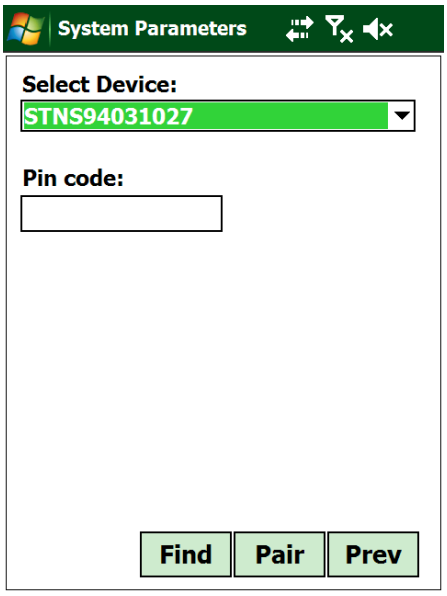


- If Bluetooth communication was selected, Click ***Find*** to start Searching for bluetooth devices.

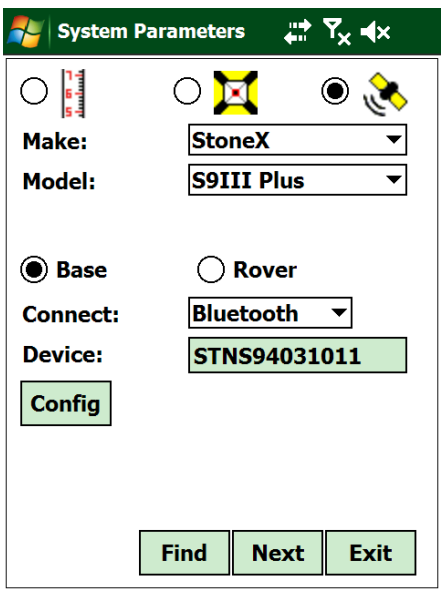


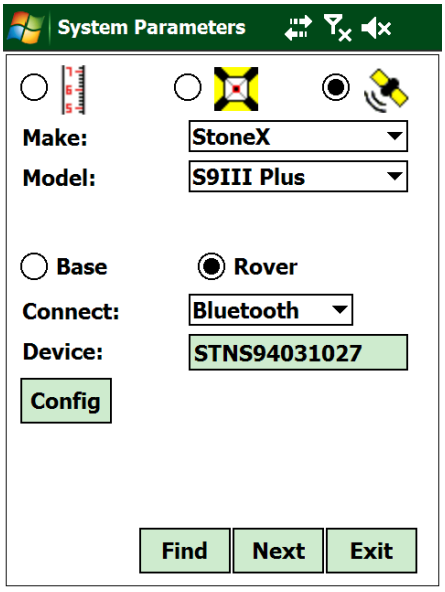
- Assign the appropriate Serial number for your Base/Rover and Click ***Pair***



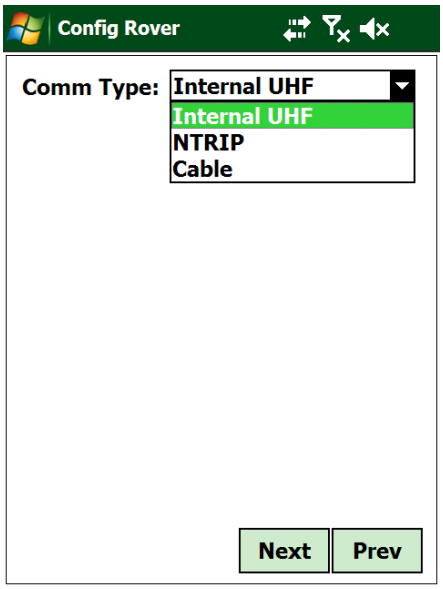


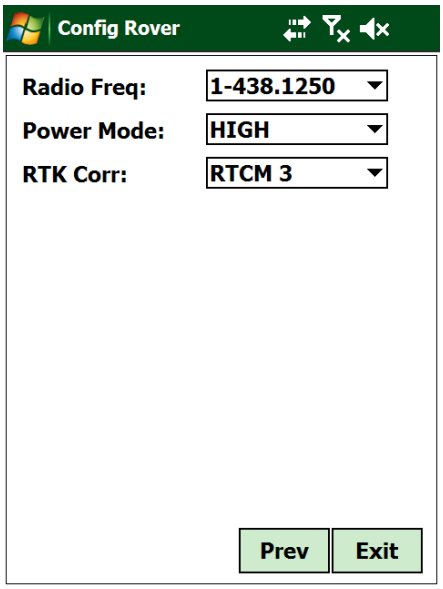
- Once both Devices have been paired and assigned





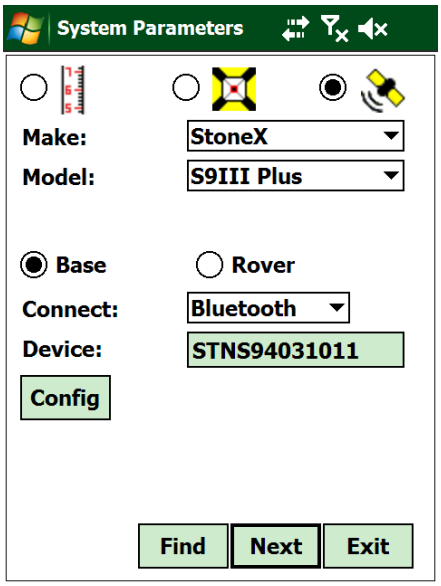
- Click ***Config*** to change Correction settings/type and ***Next*** to change settings.

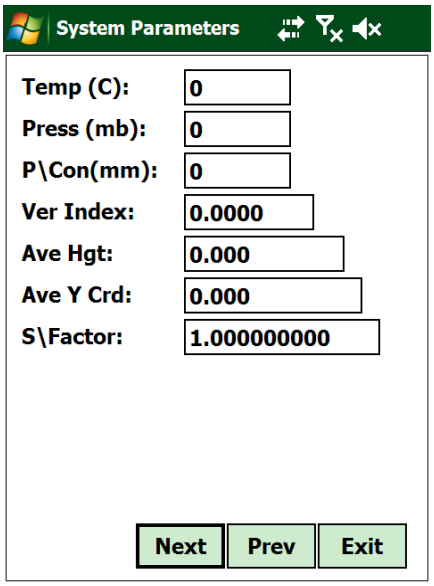


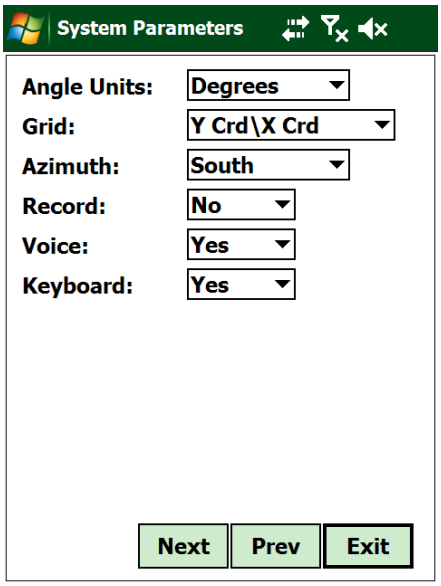


- Once you have matched the radio settings click ***Exit.***

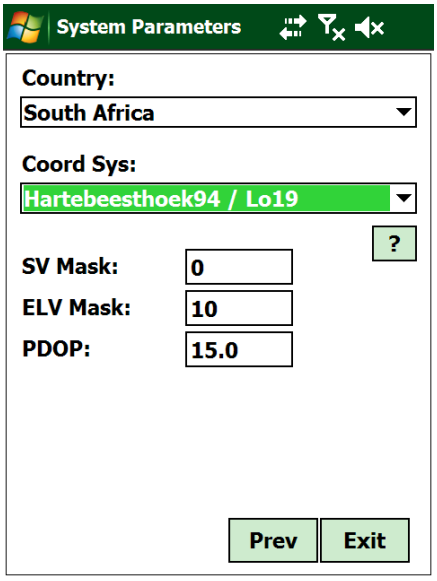
- Proceed through the Menu by Clicking ***Next*** to Finish your System Settings.





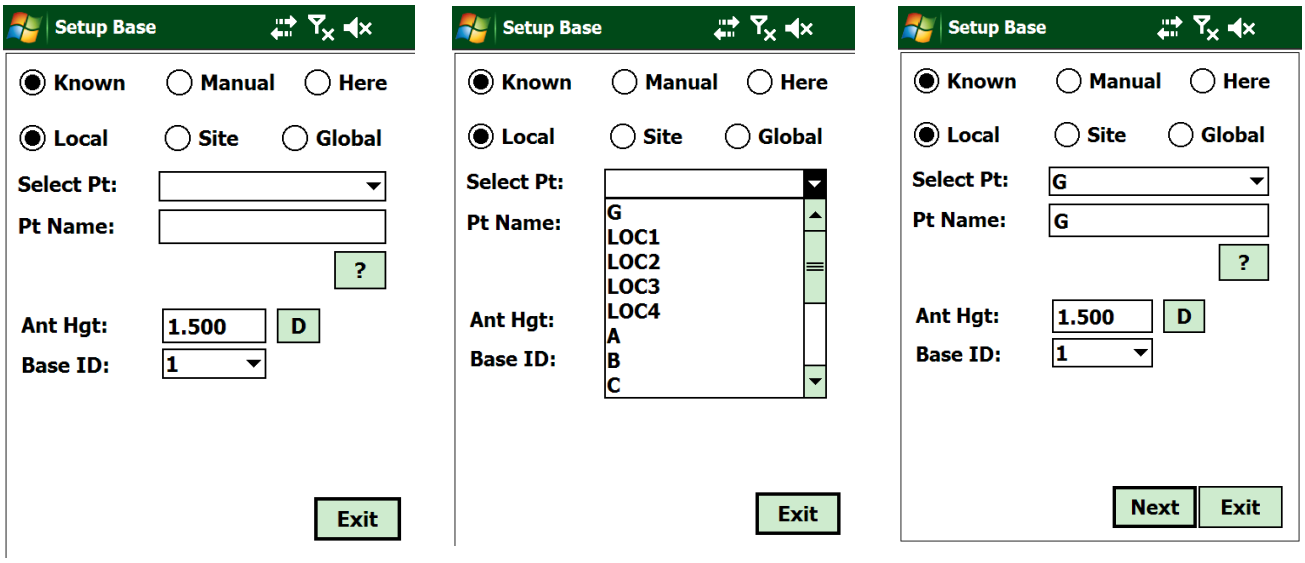


- Select the correct Coordinate System and click ***Exit*** to save settings

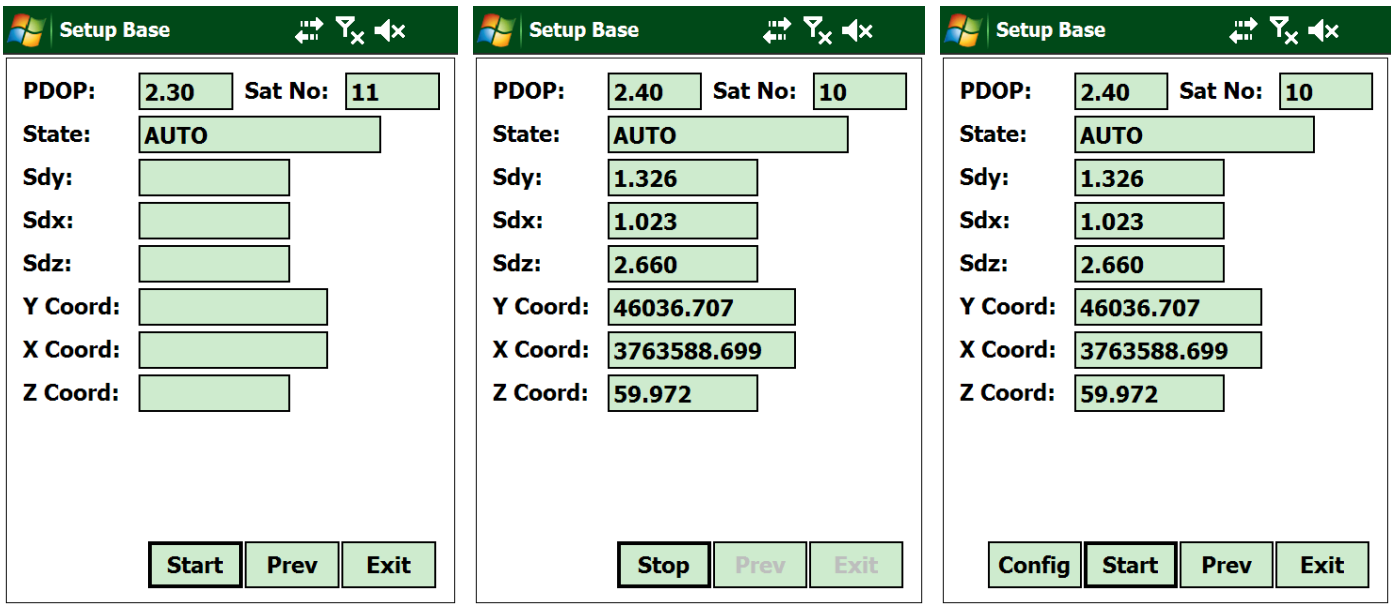


How to Setup your Base for RTK Survey:

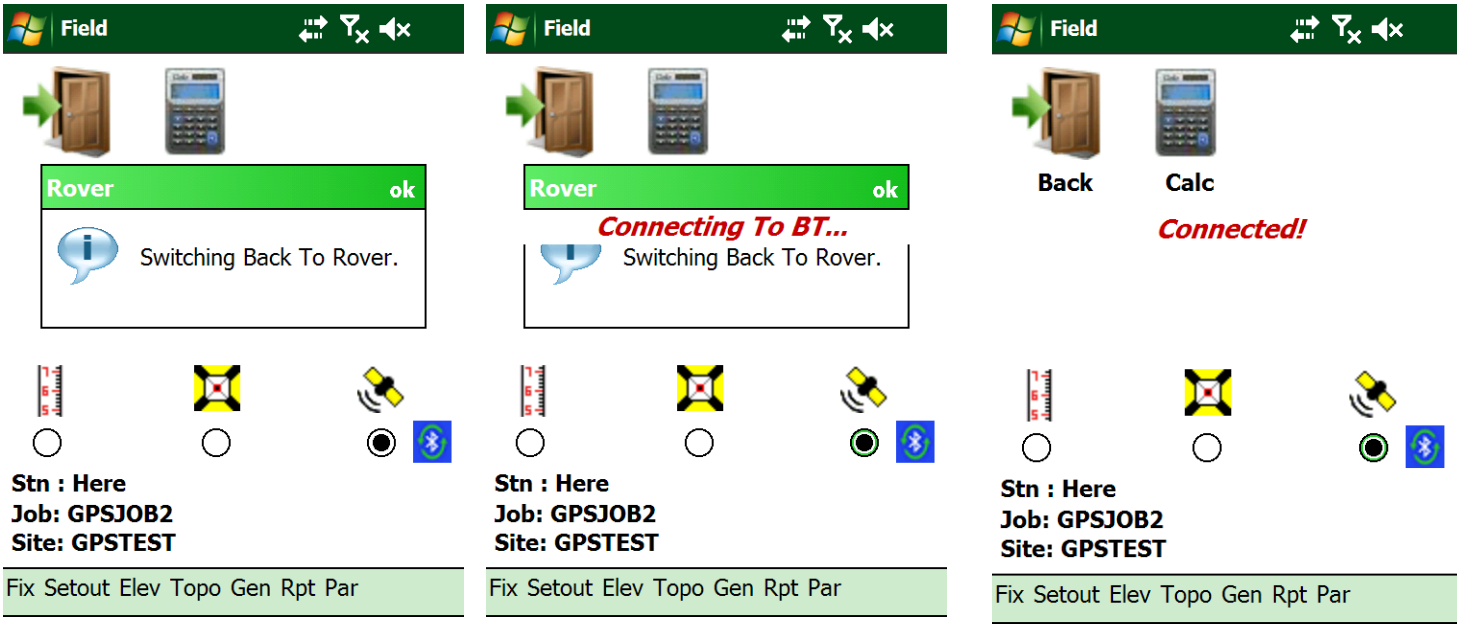
- In the **Field** screen Click ***Fix > Setup Base***
- Choose your setup method, *In this example "**Known**" is used.*
- Select your known position and type in your Base Antennae Height
- Click ***Next***



- Click ***Start*** to Start Logging data for Base position and ***Stop*** when ready.

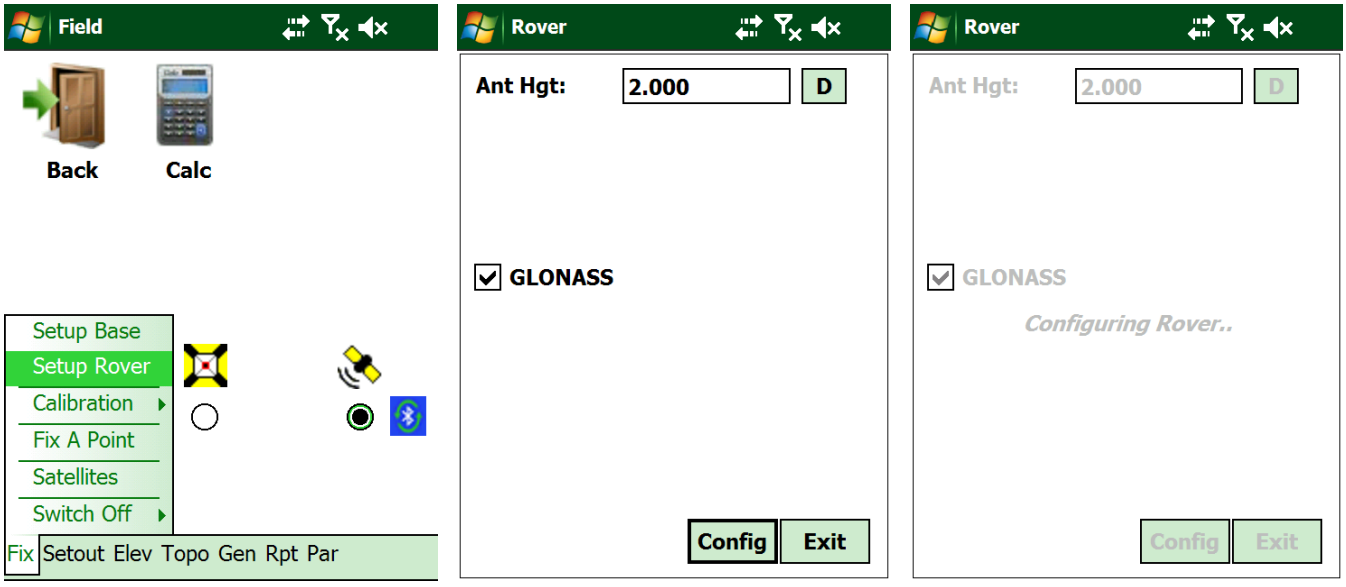


- Click ***Config*** to configure your base's position and to start Surveying
- Ceaser will automatically connect to your rover.



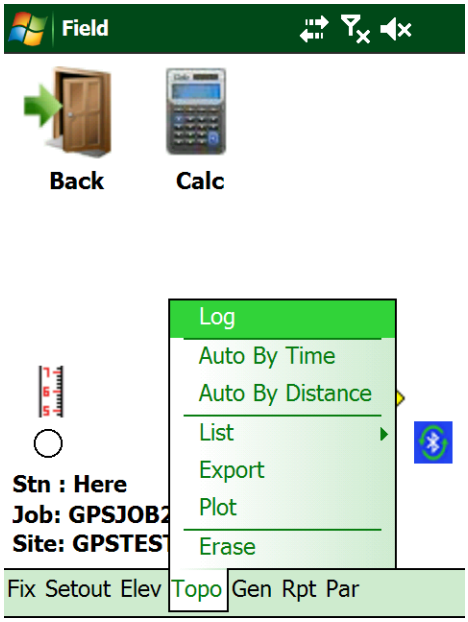
Remember to apply all configurations that were made in "System Setup" to your GPS unit.

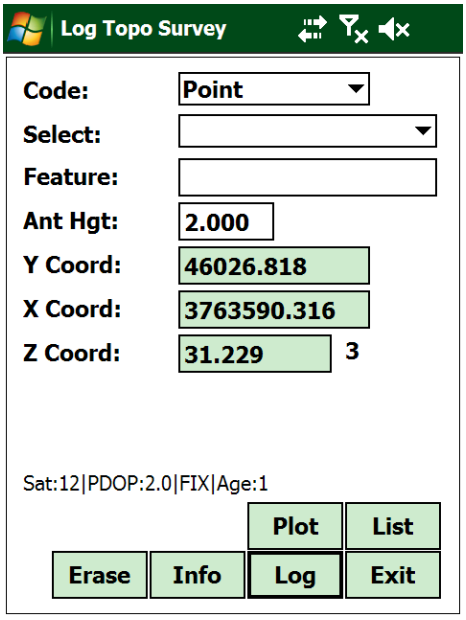
- From the Field Menu, Click ***Fix*** > ***Setup Rover.***This will reconfigure your GPS unit to the selected configuration in "***System setup***".
- Click ***Config*** to send the configuration to the GPS unit.



How To Check your Fix Status

- To check your fix, from the **Field Menu,** Click ***Topo >Log.***
- Look at the Status Display at the bottom of the Screen





Sat:14|PDOP1.6|FIX|Age:2

Sat: Amount of Satellites being used

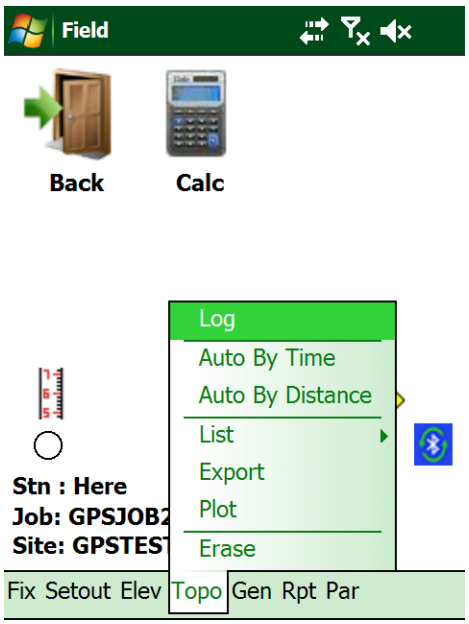
FIX: Fix status, eg. FLOAT,DGPS,AUTO

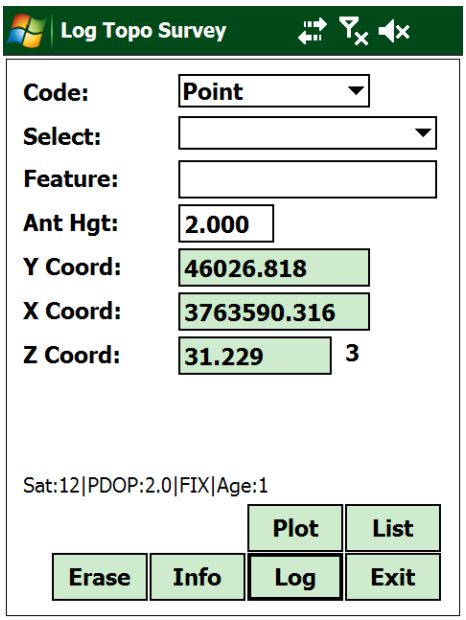
PDOP:PDOP rating

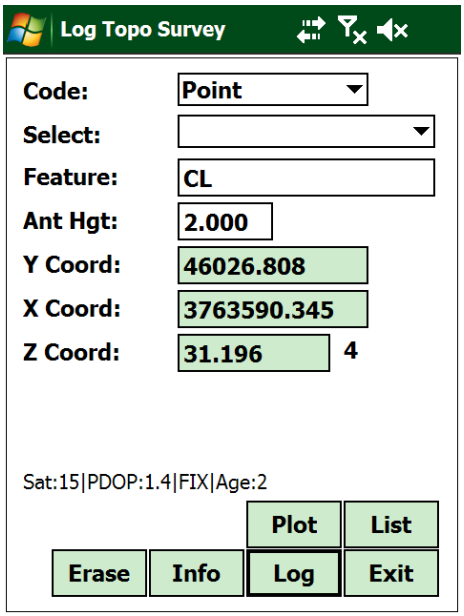
Age: Time of last correction message recieved

How To Log a point:

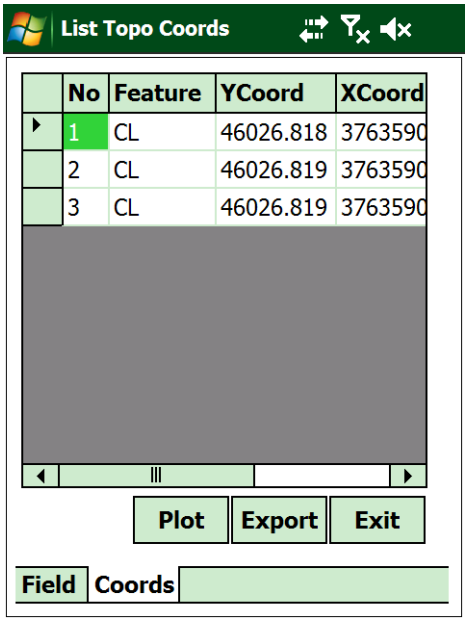
- From the **Field Menu,** Click ***Topo >Log.***
- Type in your Feature name and click ***Log***

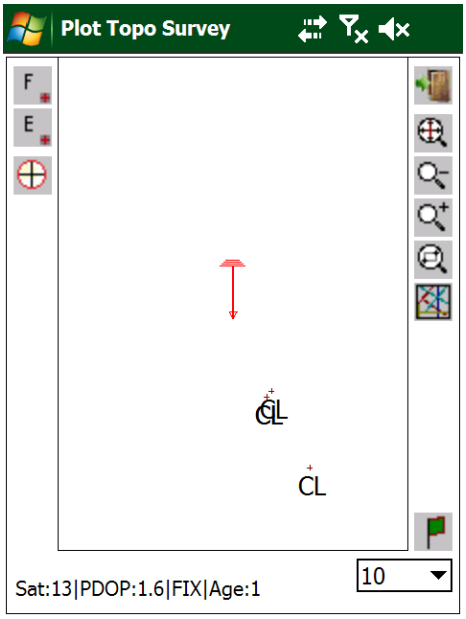






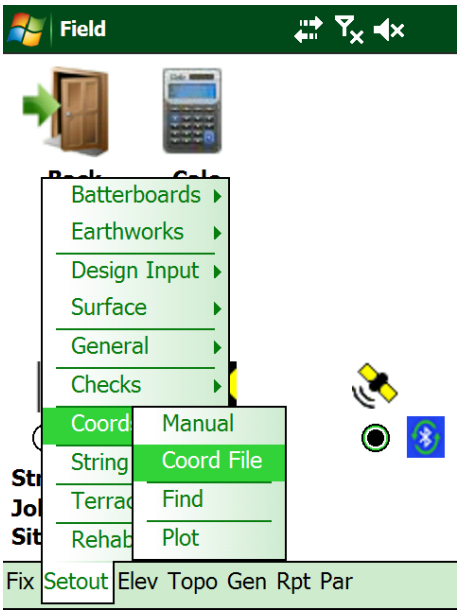
- Click ***List*** to view points and ***Plot*** to View your coordinates via Map View

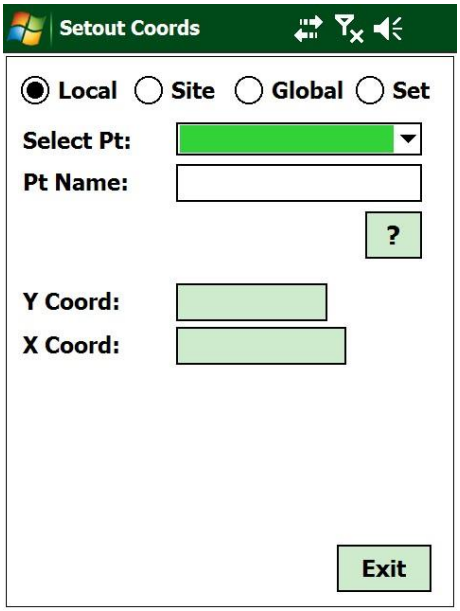


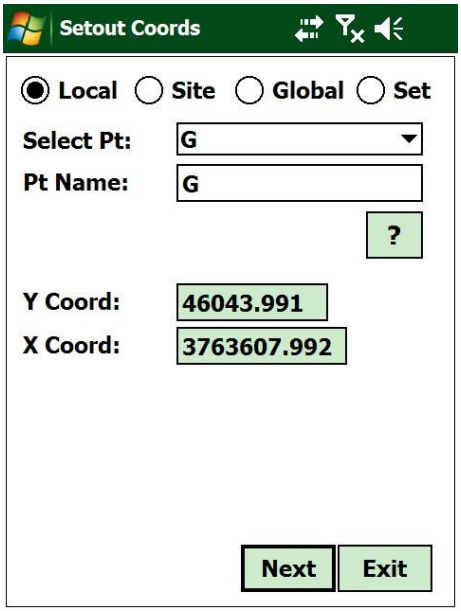


How To Setout a point:

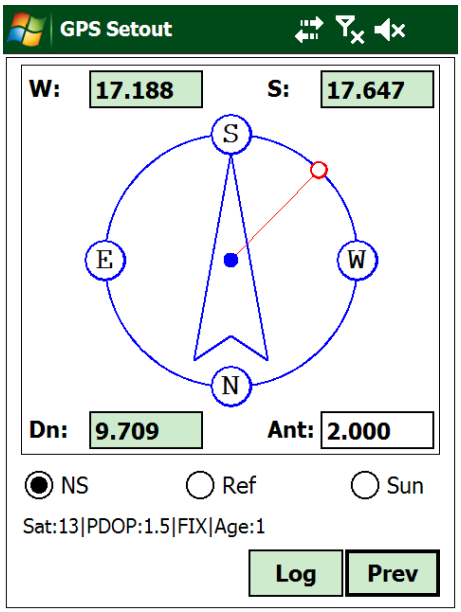
- From the **Field Menu,** Click ***Setout > Coords > Coord File***

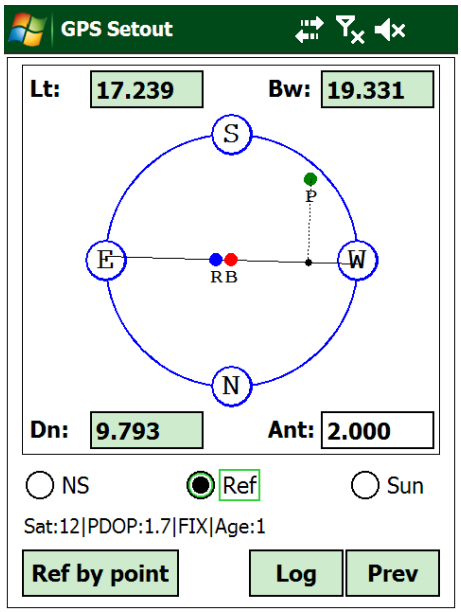


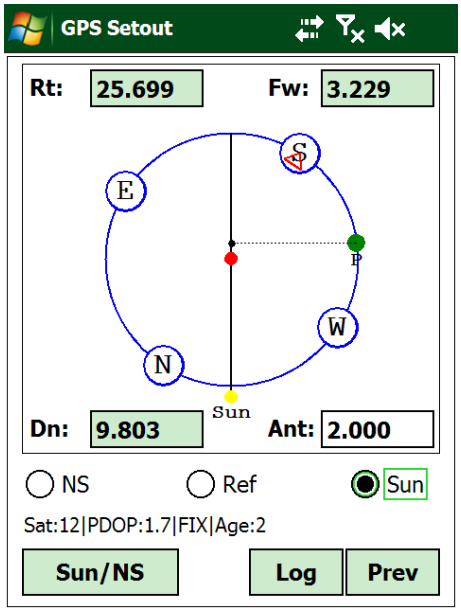




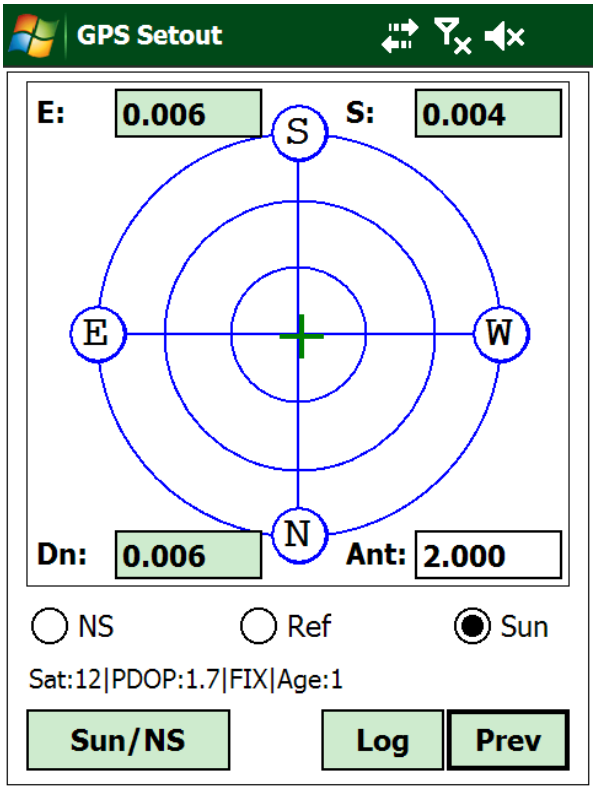
Choose from 3 different viewing options







When you are close to the setout point your display will change to this



Click *Log* to Store Point data

North/South: This view uses the standard North, South, East and West to help direct you to a point

Reference Line: With this view an imaginary line is drawn from the Base or Manually selected coordinate to the current Rover position. The program will then guide the Surveyor with directions and distance in relation to this imaginary line.

Sun/Shadow Method: Using the direction of the shadows the program will guide the Surveyor to the setting out point.